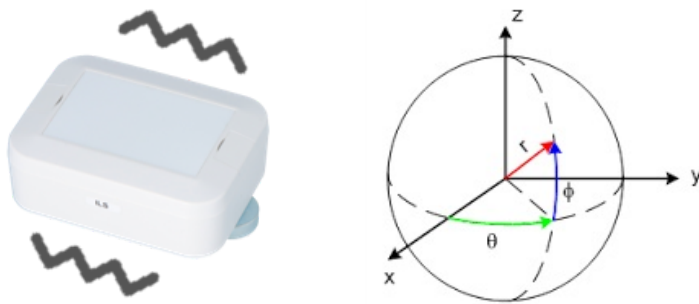# Inclin'O

support.watteco.com/inclino-r6163/

Inclin'O sensor

Presentation

The Inclin'O sensor is a LoRaWAN class A sensor that uses a disposable 3.6V A-type battery as power supply, and includes an internal antenna.

> Initially used to check the closing state of the roof windows, It constantly measures the displacement of the **vertical angle of the sensor** (**Φ**). The current angle displacement is measured **relative to the initial position of the sensor, awaken from storage mode, or reset to factory state**. The initial reference 0° can therefore be a none-horizontal position.

With its **default configuration** Inclin'O is configured to report :
- a secured alarm each time **the threshold of 40 degrees** is crossed on exceed.
- a secured alarm each time **the threshold of 10 degrees** is crossed on fall.
- a secured alarm if the voltage of the battery goes under the 2.7V threshold, with a report of the battery level every weeks.

However, angle shift reports or alarms can be reconfigured for any specific use.

Since software revision v3.5.2r6163, ***the sensor is able to set it's "zero degree" angle referencing mode****:*

- *Set on each sensor startup/reboot (Historical mode)*
- *Taken from current stored reference*
- *Set and Stored when asked by user :*
  - *Through HMI with 2 magnet passages (Cf Human Machine Interface)*
  - *or with specific downlink (Cf Applicative Layer)*

*Since software revision v3.5.2r6163, **the sensor is also able to measure chocks (accelerations) that occurs on it**. Even if the configuration stays the same on the default products, new clusters and commands are available to change/activate parameters of Chocks measurements. (See also family code below).*

When chocks measurement is activated, the sensor will monitor permanently chocks that occurs on it. The maximum amplitude of dynamic acceleration is evaluated from first chocks until end of a period given by the "Min report" parameter of the configured report. Following parameters can be configured for the survey:

- Sampling frequency. Default and adviced for a good efficiency/consumption tradeoff: 100Hz
- Aceleration Range from +/- 2g to +/- 16g
- A common threshold that is used for each axes.

Resulting measurement is the modulus accelerations from the 3 axes : $\sqrt{AccX^2 . AccY^2 . AccZ^2}$

Family code

The family code of Inclin'O devices is: 50-70-201-xxx

Inclin'o sensors can be delivered with a different default configuration that makes chocks and angle measurement. This alternate default configuration is available when sensor is tagged with the "36-70-201-000" identifier (sticker). See also Applicative Layer and Default configutrations.

LoRaWAN release

v1.0.2 Region Parameter rev B
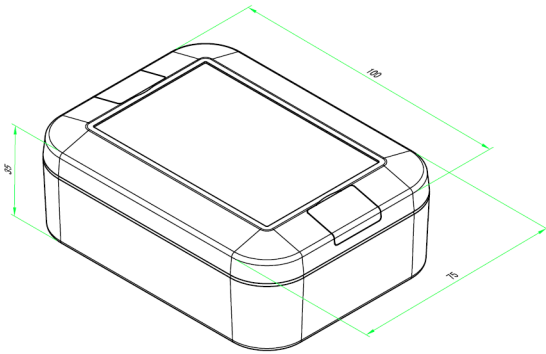
Casing

Flammability rating: UL94V0
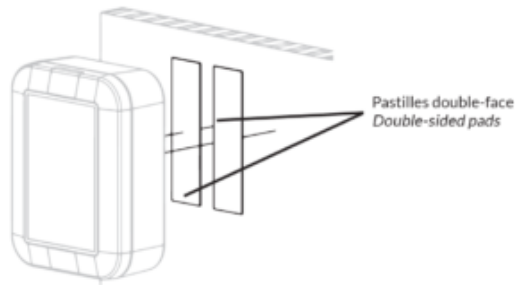Ingress protection: IP68
Dimension: 100x75x35mm
Weight : 130g without fastening solution / 180g with 2 magnets (magnets kit (71-70-132-000))
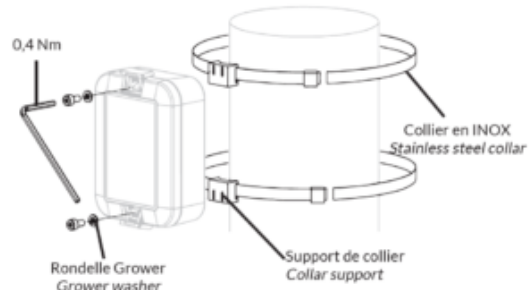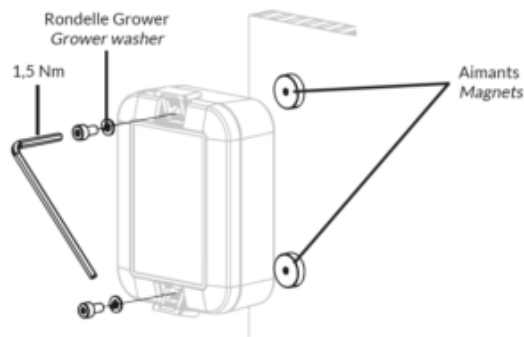
Installation and operation

Installation

The casing is intended to be installed inside or outside a building.

The casing can be fastened using the double-sided tape provided with the sensor, the optional magnet kit, the optional pole-mounting braket kit or even screwed.


Pastilles double-face
Double-sided pads

Default configuration : double-sided tape*

Rondelle Grower
Grower washer
1,5 Nm
Aimants
Magnets

0,4 Nm
Collier en INOX
Stainless steel collar
Rondelle Grower
Grower washer
Support de collier
Collar support

Optional fastening solutions: magnets kit (71-70-132-000) or pole-mounting braket kit** (71-70-133-000)

Pole-mounting bracket dimension:

18
4.3
14
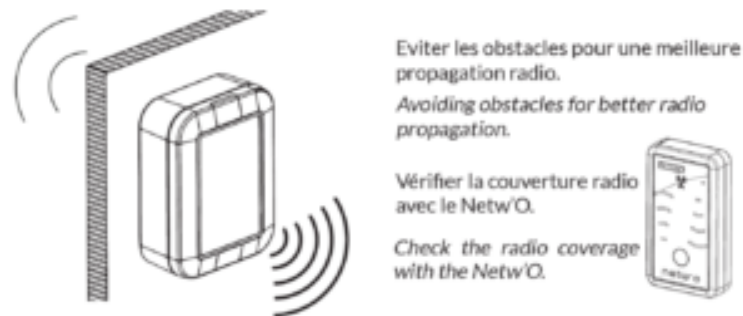9.7
A
A
11.7
1
9.5
11
1.5
2.3
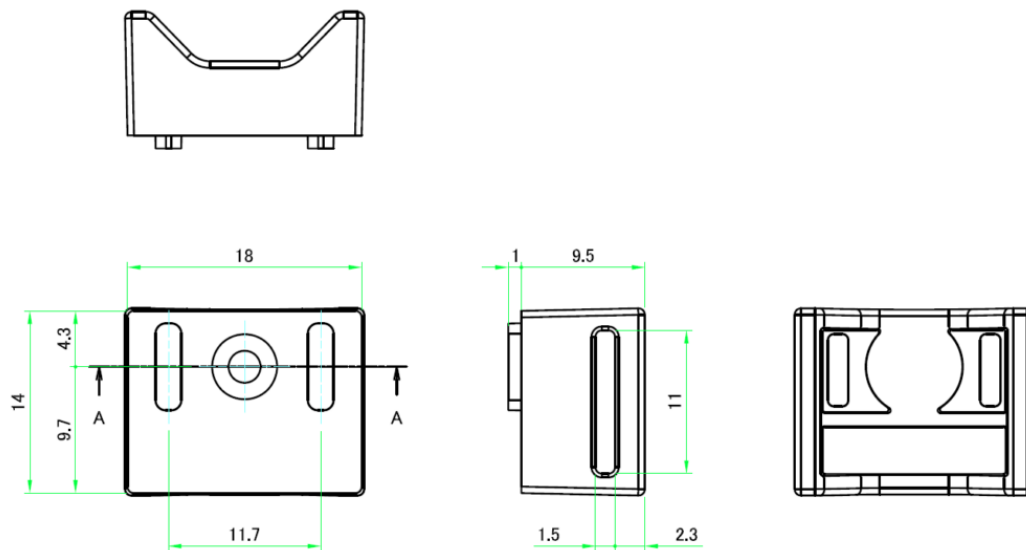
* Double-sided tape is provided along with a 3M wipe, please use this wipe to clean the area where the device is to be installed.

** No ties/collars are provided in the kit, only pole-mounting brakets. Tie/collar size: width=11mm, height=1.5mm.

Radio propagation

In order for the sensor to operate correctly, the number of obstacles should be limited in order to avoid excessive radio wave attenuation. It is also important to place the sensor as high as possible.

Eviter les obstacles pour une meilleure propagation radio.

Avoiding obstacles for better radio propagation.

Vérifier la couverture radio avec le Netw'O.

Check the radio coverage with the Netw'O.

Notice that for roof windows use case, the sensor may not be bound vertically, but even if the sensor is not in the best position, the upper situation (on the roof) of the sensor should ensure good results.

Autonomy

The information in the table below represents how long the battery can last. It is based on the default configuration at ambient temperature (+25°C) within the optimal operating range of the sensor via a LoRaWAN network (one uplink frame), when the spreading factor used is SF12.

The disposable battery has a 3.6Ah capacity, of which 85% is used.

Mode	Transmission periodicity	Battery life
Inclin'o (Angle meas 30s)	1 frame / hour	+12 years
Inclin'o (Angle meas 15mn) + Chocks monitoring (100Hz)	1 frame / hour	+10 years
Inclin'o (Angle meas 15mn) + Chocks monitoring (400Hz)	1 frame / hour	+ 5years
Inclin'o (Angle meas 30s) + Chocks monitoring (100Hz)	1 frame / hour	+9 years
Inclin'o (Angle meas 30s) + Chocks monitoring (400Hz)	1 frame / hour	+4,5 years

.

Human Machine Interface

The Inclin'O sensor has a buzzer that allows it to "communicate" with the user.

A reed switch is available under the sticker **"ILS"**.

It is possible to use a **magnet** to activate it and makes specific actions on the sensor (Switch off, switch on, Re-associtation…). When the reed switch is activated, the buzzer rings quickly.

Device startup and stop

To Start-up the device, it is necessary to put a magnet on the side of the sensor during one second (on the right side of the device). The buzzer rings quickly during this step. After this second, the buzzer stops and rings slowly until the association is done.

To switch off the device, place the magnet in front of the "ILS" label during 5 seconds. After 5 seconds, the device rings 5 times slowly and powers off.

The table below describes the actions to be performed on the reed switch to disable or enable the storage mode.

Action	Magnet	Buzzer
Switch ON (disable storage mode)	1 second	▶ 0:00 / 0:00 ⸺ 🔊 ⋮
Switch OFF (enable storage mode)	5 seconds	▶ 0:00 / 0:00 ⸺ 🔊 ⋮

When the sensor is trying to associate with a network, it emits the following sound:

▶ 0:00 / 0:00 ⸺ 🔊 ⋮
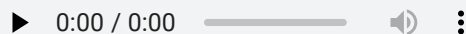
Once the association is completed, the buzzer makes the following sound:

▶ 0:00 / 0:00 ⸺ 🔊 ⋮
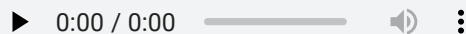
A reed switch (or magnetic switch) is available. A magnet can be used to activate it and perform specific actions on the sensor (switch off, switch on, reassociation…).

Configuration mode

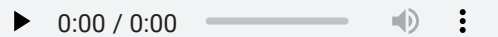**Configuration: "void" frames are sent every minute for 10 minutes.**

Standard reports are disabled in this mode.

Configuration mode

|	
Way to trigger it	One passage of the magnet near the reed switch or specific ZCL command
Way to stop it	Another passage of the magnet or specific ZCL command
Effects on the sensor	▶ 0:00 / 0:00 ———— 🔊 ⋮
Duration	The configuration mode lasts 10 minutes

Reassociation

A reassociation procedure can be requested if no downlink frame is received by the sensor during a given periodicity (4 days by default) or if a given number (100 by default) is reached or in case of failure (no acknowledgement received) by sending an applicative frame to the sensor or via the sensor's HMI.

The sensor keeps the AppEUi and DevAddr configured, Confirmed/Unconfirmed configuration and all applicative configurations. However, LoRaWAN configurations (channel, data rate…) are lost

ReAssociation Mode

Way to trigger it	Three passages of the magnet near the reed switch or ZCL command from LoRaWAN cluster.
Effects on the sensor	▶ 0:00 / 0:00 ———— 🔊 ⋮
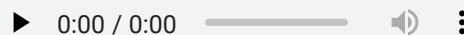
Factory reset

A factory reset is available on Watteco's sensors. It deletes all the applicative settings saved in the flash memory (i.e. configured batches and reports will be deleted).

The sensor keeps the AppEUi and DevAddr configured. However, LoRaWAN configurations (channel, data rate…) and applicative configurations are lost.

Factory reset

Way to trigger it	Two quick passages and a very long passage (until the sensor rings for the reset) of the magnet near the reed switch
Effects on the sensor	▶ 0:00 / 0:00 ———— 🔊 ⋮
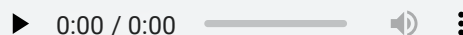
Set zero ° angle reference (firmware > v3.5.2.r6163)

It is possible to set the Zero ° angle displacement to current position of the sensor through two short passages of the magnet. This referencing procedure can be actuated in anystate of the sensor, even stopped.

Factory reset

Way to trigger it	Two quick passages

Effects on the sensor
1 Two Magnet passages sound return
2 Melody of referencing start
3 Melody of end of referencing

▶ 0:00 / 0:00 ——————— 🔊 ⋮

Applicative layer

> Codecs are available to decode frames: **Downloads**

The Inclin'O device implements mainly an "Analog Input" cluster associated to angle displacement measurement on, a "Number cluster" associated with last Chocks Maximum Acceleration measurement and An "occupancy cluster" is also implemented that manage a boolean status of chocks presence.

Inclin'O integrates the following clusters:

Cluster	Cluster name	Managed attributes
0x0000	Basic	All
0x0050	Configuration	All
0x8004	LoRaWAN	All
0x000C	AnalogInput (for vertical angle displacement) *With an application specific command for angle referencing.*	All attributes except: 0x8004: Chocks parameters, only since r6163 *0x8003: Power duration **unused***
0x800E (SInce r6163)	Number (U16) (for chocks acceleration reports [mg]) Chocks measurement are given in mg as: √ AccX² . AccY² . AccZ²	All
0x0406 (SInce r6163)	Occupancy (for Chocks/vibration status) *1: Chocked or Vibrating, 0: Idle.*	All

Setting Angle reference

From r6163 The inclin'o can set its current Angle Referencing mode using an application specific command on cluster Analog input. The general format of the command s the following one:

> **11 50 000C FF 01 xx**

where xx can be:

- **00: Reset reference on each reboot/startup (historical behaviour of skydome)**
- **01: Reset reference now and store it, then use stored one on next inits (like 02)**
- **02: Use stored one on each init**

Default configurations

A default configuration is set:
Inclin'o historical 10° / 40° thresholds for Skydome

- **The device reports each crossing on exceed of 40° angle displacement measured from position at sensor startup.**
- **The device reports each crossing on fall of 10° angle displacement measured from position at sensor startup.**
- **The device reports the battery level once a week, and will send an alarm message if the 2.7V threshold is crossed.**

Every change made to the default configuration must comply with the legal duty cycle (for example, the most restrictive in the EU is 0.1%, which corresponds to approximately 1 frame per hour with SF12)

From r6163 a mode with chocks measurement can be configured or activated:
Inclin'o with shocks monitoring and periodic angle reading

The configuration embedding chocks measurements is referenced as (36-70-201-000). This alternative configuration uses Batch reports, with specifics actions to accelerate Batch transmission when chocks are occuring:

- **The device records its current Angle from origin with a period of 24h, measured once per 15 minutes and also recorded if varying of more than 5°**
- **The devices survey chocks at 100Hz sampling, with a range of +/-16g on each axes, and a threshold of 1116mg.**
- **When a first chock is detected, the batch transmission is forced. It contains the firt chock evaluation. Then following chocks are recorded in the batch that is sent each 3 minutes, until no more chocks occur for more that 4 minutes**

Detailed default configurations

Notice that ZCL configuration frames in following descriptions are prefixed with a frame size byte. They can be used as it is for Watteco FOTA configuration tool, but the size prefixe should be removed when frame is used for downlink. In both cases commented lines '#' must not be used.

Inclin'o historical 10° / 40° thresholds for Skydomes

. Set "not confirmed" except for confirmed alarms with 3 retries (if any)
08 11 05 8004 0000 08 00
08 11 05 8004 0001 20 03
#
. Delete all configurations (Batch and Standard)
06 11 50 0050 02 03
#
LIS2DE TAP detection (Think about devopt LIS2DE et TAP bit activation (cf InfoMem.7010xxxVyy))
TAP inactivated and use 100Hz for angle measurement (faster measurement):
0x1403 : (b00 0101 00 / 0 0000011) Idle/100Hz/2g/(3*16)=48mg
09 11 05 000c 8004 19 1403
#
------------------------ STANDARD REPORTS ------------------------
. POWERDESC [mV] # . Periodic MAX = 7j => 10080mn => xA760; MIN = 10mn => 0x800A
. Length of remaining payload (for 0x41 type): 0x08
. ALARM on power treshold : 2,7v (hyst 100mV)
RP : NewCfg/Reserved/ShortCause/SecuredIfAlarm/AllNotSecured/HeaderKept/NotBatch :
b 1 0 01 1 0 0 0 ==> x98
CSD : IsAlarm/OnExceed/OnFall/Threshold/Slot0 : b 1 1 1 10 000 ==> xF0
Disposable battery field index : 0x04
THRS: 2700 : 0x0A8C; HYST: 100 mV : 0x0064
OCC : 1
14 11 06 0050 98 0006 41 800A A760 07 F0 04 0A8C 0064 01
#
. ANGLE DISP (LIS2DE12TR) (Report aperture(analoginput): Alarm Open [(> 40° + 2,5)] # Min 30s et periodic 12h (720 min ==> x82D0)
. RP : NewCfg/Reserved/ShortCause/SecuredIfAlarm/AllNotSecured/HeaderKept/NotBatch : b 1 0 01 1 0 0 0 ==> x98
. CSD : IsAlarm/OnExceed/NotOnFall/Threshold/Slot0 : b 1 1 0 10 000 ==> xD0
. THRS: 40,00°: 0x42200000; HYST: 2,50°: 0x40200000
. OCC : 1
16 11 06 000c 98 0055 39 001E 82D0 D0 42200000 40200000 01
#
. ANGLE DISP (LIS2DE12TR) (Report aperture(analoginput): Alarm close [(< 10° + 2,5)] # Min 30s et periodic 12h (720 min ==> x82D0)
. RP : NewCfg/Reserved/ShortCause/SecuredIfAlarm/AllNotSecured/HeaderKept/NotBatch : b 1 0 01 1 0 0 0 ==> x98
. CSD : IsAlarm/NotOnExceed/OnFall/Threshold/Slot1 : b 1 0 1 10 001 ==> 0xB1
. THRS: 10,00° : 0x41200000; HYST: 2,50° : 0x40200000
. OCC : 1
16 11 06 000c 98 0055 39 001E 82D0 B1 41200000 40200000 01

Inclin'o with shocks monitoring and periodic angle reading (>= r6163 and tag 36-70-201-000)

```
# . Set "not confirmed" except for confirmed alarms with 3 retries (if any)
08 11 05 8004 0000 08 00
08 11 05 8004 0001 20 03
#
# . Delete all configurations (Batch and Standard)
06 11 50 0050 02 03
#
# LIS2DE TAP detection
# Note about TAP configuration examples:
# 0x9403 : (b10 0101 00 / 0 0000011) Click/100Hz/2g/(3*16)=48mg
# 0x5403 : (b01 0101 00 / 0 0000011) Chock/100Hz/2g/(3*16)=48mg
# 0x9C03 : (b10 0111 00 / 0 0000011) Click/400Hz/2g/(3*16)=48mg
# 0xA003 : (b10 1000 00 / 0 0000011) Click/1620Hz/2g/(3*16)=48mg
# 0x6003 : (b01 1000 00 / 0 0000011) Chock/1620Hz/2g/(3*16)=48mg
# 0x5503 : (b01 0101 01 / 0 0000011) Chock/100Hz/4g/(3*32)=96mg
# 0x5D03 : (b01 0111 10 / 0 0000011) Chock/400Hz/8g/(3*62)=186mg
# 0x5706 : (b01 0101 11 / 0 0000110) Chock/100Hz/16g/(6*186)=1116mg
# 0x6306 : (b01 1000 11 / 0 0000110) Chock/1620Hz/16g/(6*186)=1116mg
# 0x5E03 : (b01 0111 10 / 0 0000011) Chock/400Hz/8g/(3*186)=558mg
# 0x5F06 : (b01 0111 11 / 0 0000101) Chock/400Hz/16g/(6*186)=1116mg
09 11 05 000c 8004 19 5706
#
# . Occupancy binded to sur chocks sensor.
# ie: when chocks occur the "occupied is set" and after a programmable delay without
chocks, the "occupied is unset"
#
# UnOcc to Occ delay: 0s (Will reconfigure "fast batches (ACTION 0)" after this delay
without chocks notification
09 11 05 0406 0011 21 0000
# Occ to Unocc delay: 4minutes (0xF0 sec) (> FAST BACTH period see 3mn (8003) below!).
# Will reconfigure "SLOW batches (ACTION 1)" after this delay without notification
09 11 05 0406 0010 21 00F0
#
# ------------------------- ACTIONS altering BATCH REPORT -------------------------------
#
# ACTION 0: FAST batch config for chocks
# ACCELERATION (TAP/LIS2DE) ** Acc(mg) **
# Min 5s => 0x0005, Max 3mn, Delta=0, resol=1, Tag Label 0, Tag Size 3, Type U16 6
19 11 05 0050 FF00 41 11 11 06 800E 15 0000 00 0005 8003 0000 0001 03
#
# ACTION 1: SLOW batch config for chocks (big max)
# ACCELERATION (TAP/LIS2DE) ** Acc(mg) **
# Min 1s => 0x0001, Max 24h, Delta=0, resol=1, Tag Label 0, Tag Size 3, Type U16 6
19 11 05 0050 FF01 41 11 11 06 800E 15 0000 00 0001 85A0 0000 0001 03
#
# ACTION 2: Batch Force reports
0D 11 05 0050 FF02 41 05 11 50 0050 08
```

```
#
# ------------------------ ACTIONS TRIGGER CONFIGURATION ----------------------------
# -------------- ACCORDING CHOCKS EVENTS MAPPED TO OCCUPANCY CLUSTER --------------
----
#
# NOTE: New action function used here, available since this INclin'o Chocks revision:
# Execute action "Without Save" = 0x04 can be used instead of Execute action = 0x00
# ==> If any required ZCL action should be saved it won't be
# Concerned commands : Write saved parameter, Configre STD report, Configure Batch
report
#
# ---> A Chock has set occupancy back to 1 : TILT is being chocked or moving =>
Acceleration reports are faster
# . Periodic MAX = Inf => xFFFF; MIN = 10s => 0x000A
# . ALARM on treshold HIGH: 1; hyst 00
# RP : NewCfg/Reserved/ShortCause/SecuredIfAlarm/AllNotSecured/HeaderKept/NotBatch :
b 1 0 01 1 0 0 0 ==> x98
# CSD : NotIsAlarm/OnExceed/NotOnFall/ThresholdWAction/Slot1 : b 0 1 0 11 001 ==> x59
# THRS(Bitmap Mask): 1 : 0x01; HYST(Bitmap Pattern): 0 : 0x01
# OCC : 1
# ACTION: Without report (0x88), StopOtherActions(FF) /
# StartDelayBeforeForceBatch(010001) / Force batch report(0002) / Set batch config wo
save(ACTION 0: 0400)
19 11 06 0406 98 0000 18 000A FFFF 59 01 01 01 88 FF 010001 0002 0400
#
# ---> No chock from a while occupancy back to 0 : TILT is immobile => Stop acceleration
report (big Max)
# . Periodic MAX = Inf => xFFFF; MIN = 10s => 0x000A
# . ALARM on treshold LOW: 1; hyst 0
# RP : NewCfg/Reserved/ShortCause/SecuredIfAlarm/AllNotSecured/HeaderKept/NotBatch :
b 1 0 01 1 0 0 0 ==> x98
# CSD : NotIsAlarm/NotOnExceed/OnFall/ThresholdWAction/Slot2 : b 0 0 1 11 010 ==> x3A
# THRS(Bitmap Mask): 1 : 0x01; HYST(Bitmap Pattern): 0 : 0x01
# OCC : 1
# ACTION: Without report size 3 (0x83), StopOtherActions(FF)/Set batch config wo
save(0401)
# ==> 83 FF 0401
14 11 06 0406 98 0000 18 000A FFFF 3A 01 01 01 83 FF 0401
#
# ------------------------ STANDARD REPORTS --------------------------------------------
# . POWERDESC [mV] # . Periodic MAX = 7j => 10080mn => xA760; MIN = 10mn => 0x800A
# . Length of remaining payload (for 0x41 type ): 0x08
# . ALARM on power treshold : 2,7v (hyst 100mV)
# RP : NewCfg/Reserved/ShortCause/SecuredIfAlarm/AllNotSecured/HeaderKept/NotBatch :
b 1 0 01 1 0 0 0 ==> x98
# CSD : IsAlarm/OnExceed/OnFall/Threshold/Slot0 : b 1 1 1 10 000 ==> xF0
# Disposable battery field index : 0x04
```

```
# THRS: 2700 : 0x0A8C; HYST: 100 mV : 0x0064
# OCC : 1
14 11 06 0050 98 0006 41 800A A760 07 F0 04 0A8C 0064 01
#
# ------------------------ STARTUP BATCH REPORT ---------------------------------------
#
# . ACCELERATION (TAP/LIS2DE) ** Acc(mg) **
# Min 1s => 0x0001 (Note: this min sets the min maximum acc measurement when chocks
occures),
# Max 24h, Delta=0, resol=1, Tag Label 0, Tag Size 3, Type U16 6
11 11 06 800E 15 0000 00 0001 85A0 0000 0001 03
#
# . ANGLEDISP (TAP/LIS2DE) ** Angle (°) **
# Min 4h => 0x80F0(angle measurement period), Max 24H, Delta=5 (0x40a00000) [1
(0x3f800000)], resol=0,1(0x3dcccccd), Tag Label 1, Tag Size 3, Type Float 12
15 11 06 000C 1D 0055 00 80F0 85A0 40a00000 3dcccccd 0B
#
# Codec params: 3 0,1,6,ACCmg 1,0.1,12,Deg
```

Alternate configurations

From revision 6163, Inclin'O sensor has got a specific command to switch between the two above configurations.

For a standard default configuration:

- Set "Inclin'o with shocks monitoring ad periodic angle reading" : 11500050F101
- Set Back to "Inclin'o historical 10° / 40° thresholds for Skydomes": 11500050F100

For tagged 36-70-201-000 sensors, default configuration is:

- Set "Inclin'o historical 10° / 40° thresholds for Skydomes": 11500050F101
- Set Back to "Inclin'o with shocks monitoring ad periodic angle reading" : 11500050F100

Frame examples

All frames have to be sent on port 125

(Please, Try and see also Watteco Online codecs)

Standard report

Report

Report on angle displacement crossing programmed threshold

Received payload is: **11 8a 000c 0055 39 42fe23d7 98 d0**

. **0x11 = FCtrl (EndPoint 0)**
. **0x8a = Report is an alarm (Most significant bit is set)**
. **0x42fe23d7 = Current vertical angle displacement (127°) (IEE754 float)**
. **0x98 =**
NewCfg/Reserved/ShortCause/SecuredIfAlarm/AllNotSecured/HeaderKept/NotBatch: b 1 0 01 1 0 0 0
. **0xD0 = IsAlarm/OnExceed/NotOnFall/Threshold/slot0: b 1 1 0 10 000**

Configuration

Configure 27,5° Threshold crossing

Report angle displacement (analoginput) alarm, when angle crosses threshold or once each 24h (1440 min ==>0x85A0):

The angle displacement is given by EndPoint 0 (0x11) on Cluster "Analog Input" 0x000C, and Attribute "present value" is 0x0055.

Applicative payload to send is: *11 06 000c 98 0055 39 0002 85A0 F0 41dc0000 40200000 03*

. **0x98 =**
NewCfg/Reserved/ShortCause/SecuredIfAlarm/AllNotSecured/HeaderKept/NotBatch: b 1 0 01 1 0 0 0
. **0xF0 = IsAlarm/OnExceed/OnFall/Threshold/Slot0 : b 1 1 1 10 000 ==> xF0**
. **0x41dc0000 = 27,50° Threshold**
. **0x40200000 = 2,50° Hysteresis around threshold**
. **0x03 = Number of succesive measured occurences crossing to set an alarm**

Expected response: **11 07 000c 00 00 0055**

To disable configuration on slot 0 : 11 06 000c 80 0055 39 0000 0000 00

Configure a simple periodic report on angle displacement change

Report the angle displacement value when angle changes more than 10°, and report it at least least every 2 hours (120 min ==> 0x8078), but no more than one report each 30seconds (0x001E)

The angle displacement is given by EndPoint 0 (0x11) on Cluster "Analog Input" 0x000C, and Attribute "present value" is 0x0055.

 Applicative payload to send is: *11 06 000c 00 0055 39 001E 8078 41200000*

. 0x00 = NotNewCfg/NotBatch : b 0 0 0 0 0 0 0 0
. 0x41200000 = 10° Variation

Expected response: 11 07 000c 00 00 0055

To disable configuration : 11 06 000c 00 0055 39 0000 0000 00000000

Batch report

Report

Inclin'o with shocks monitoring ad periodic angle reading

Input payload:

200400808049162c8a4042e0cccd000379c7a185db31f0873bc051b10bfe05beec50dc6b074b1b8005

Batch attributes/decoding parameters:

3 0,1,6,ACCmg 1,0.1,12,Deg

Decoded payload: (Try it)

```json
{
"batch_counter": 4,
"batch_relative_timestamp": 735,
"batch_absolute_timestamp": "2023-06-26T11:48:43.191",
"dataset": [
{
"data_relative_timestamp": 403,
"data": {
"value": 11352,
"label": 0,
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},
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"label": 0,
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            "label": 0,
            "label_name": "ACCmg"
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        "data_absolute_timestamp": "2023-06-26T11:48:42.191Z"
    },
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        "data_relative_timestamp": 562,
        "data": {
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            "label": 1,
            "label_name": "Deg"
        },
        "data_absolute_timestamp": "2023-06-26T11:45:50.191Z"
    }
    ]
}
```